Local integrability and linearizability of a (1:-1:-1) resonant quadratic system

Maša Dukarić¹, Regilene Oliveira² and Valery Romanovski^{1,3}

 ¹CAMTP, University of Maribor, Maribor, Slovenia
 ² ICMC - Universidade de São Paulo, São Carlos, SP, Brazil
 ³ Faculty of Natural Science and Mathematics, University of Maribor, Maribor, Slovenia

Theoretical and computational methods in dynamical systems and fractal geometry, 7th-11th April 2015

Table of contents

1 Introduction

- Normal forms
- Integrability
 - Darboux integrability
 - Jacobi Multiplier
- Linearizability

2 Results

- Theorem: Integrability
 - Integrability: Computing necessary conditions
 - Integrability: Sufficiency of conditions
- Theorem: Linearizability
 - Linearizability: Computing necessary conditions
 - Linearizability: Sufficiency of conditions
- Theorem: Existence of the first integral xy(1 + O(x, y, z))

3 Conclusion



- 2-dimensional systems:
 - quadratic systems: integrability completed
 - cubic sytems: integrability and linearizability some families of the systems studied; open problem
 - (p: −q) resonant singularities some researches



- 3-dimensional systems (integrability and linearizability not studied in such extension):
 - most studied Lotka-Volterra systems
 - Darboux integrability of three dimensional systems
 - quadratic systems in a neighborhood of a (0: -1: 1) resonant singular point (Z.Hu, M. Han, V.G. Romanovski)
 - recent studies:
 - W. Aziz, C.Christopher [2]: Lotka-Volterra quadratic systems with a (1; -1; 1), (2; -1; 1) and (1; -2; 1)-resonant points
 - W. Aziz [3]: particular family of quadratic systems with a (1:-1:1) resonant singularity

Introduction

Normal forms

$$\begin{aligned} \dot{x} &= \lambda_1 x + X_1(x, y, z) = P(x, y, z) \\ \dot{y} &= \lambda_2 y + X_2(x, y, z) = Q(x, y, z) \\ \dot{z} &= \lambda_3 z + X_3(x, y, z) = R(x, y, z), \qquad \lambda_1, \lambda_2, \lambda_3 \neq 0 \end{aligned}$$
(1)

Formal Normal Form Theorem \Rightarrow exists a change of coordinates:

$$Y = X + H(X), \tag{2}$$

where $Y = (x_1, y_1, z_1)$, X = (x, y, z) and H(X) is a series that does not contain linear terms, which transforms (1) to

$$\begin{aligned} \dot{x_1} &= \lambda_1 x_1 + Z_1(x_1, y_1, z_1) \\ \dot{y_1} &= \lambda_2 y_1 + Z_2(x_1, y_1, z_1) \\ \dot{z_1} &= \lambda_3 z_1 + Z_3(x_1, y_1, z_1), \end{aligned} \tag{3}$$

where $Z_i(x_1, y_1, z_1)$ has every nonresonant term equal to zero for i = 1, 2, 3.

Resonant terms

Monomial g_k , k = 1, ..., n, of the form $g^{(\alpha)}y^{\alpha}e_k$ with

$$<\lambda, lpha>-\lambda_k=0$$

Maša Dukarić¹, Regilene Oliveira² and Valery Romanovski^{1,3}

Integrability and linearizability: (1:-1:-1) res. quad. sys. Introduction Integrability

System $\dot{x} = Ax + f(x)$ is *locally integrable* if it has n - 1 functionally independent analytic first integrals in a neighbourhood of the origin.

Definition

System (1) is *locally integrable*: exists a transformation of variables (2) that transforms systems (1) into systems of the form

$$\begin{aligned} \dot{x_1} &= \lambda_1 x_1 (1 + O(x_1, y_1, z_1)) \\ \dot{y_1} &= \lambda_2 y_1 (1 + O(x_1, y_1, z_1)) \\ \dot{z_1} &= \lambda_3 z_1 (1 + O(x_1, y_1, z_1)). \end{aligned}$$
(4)

System (4) has analytic first integrals: by $\phi_1(x_1, y_1, z_1) = x_1^{-\lambda_2} y_1^{\lambda_1}$ and $\psi_1(x_1, y_1, z_1) = x_1^{-\lambda_3} z_1^{\lambda_1} \Rightarrow$ $\phi(x, y, z) = x^{-\lambda_2} y^{\lambda_1} (1 + O(x, y, z))$ and $\psi(x, y, z) = x^{-\lambda_3} z^{\lambda_1} (1 + O(x, y, z))$ (two independent first integrals of systems (1))

Maša Dukarić¹, Regilene Oliveira² and Valery Romanovski^{1,3}

Introduction

Integrability

Theorem[V.G. Romanovski, Y. Xia, X. Zhang (2014)]

$$\dot{x} = Ax + f(x) \tag{5}$$

(a) There exist series $\psi(x)$ with its resonant monomials arbitrary such that:

$$\mathcal{X}(\psi(x)) = \sum_{\alpha \in \mathfrak{R}} p_{\alpha} x^{\alpha}, \tag{6}$$

where p_{α} are polynomials in the coefficients of (5). (b) If the vector field (5) has n-1 functionally independent analytic or formal first integrals, then for any ψ satisfying (6), we have: $p_{\alpha} = 0$, for all $\alpha \in \mathfrak{R}$. (c) Assume that the rank of $\mathfrak{R} = \{ \alpha \in \mathbb{Z}_+^n | < \lambda, \alpha \ge 0, |\alpha| > 0 \}$ is k, i.e. $r_{\lambda} = k$, and there are k functionally independent $\psi^{(1)},\ldots,\psi^{(k)}$, such that for the corresponding coefficients in (6) hold $p_{\alpha}^{(i)} = 0$, for all $\alpha \in \mathfrak{R}$, i = 1, ..., k. Then the vector field \mathcal{X} has exactly k functionally independent analytic or formal first integrals. Maša Dukarić¹, Regilene Oliveira² and Valery Romanovski^{1,3}

Introduction

Integrability

$$\mathcal{B} = \langle p_{\alpha}^{(i)} | \ \alpha \in \mathfrak{R}, \quad i = 1, \dots, n-1 \rangle$$
, where $p_{\alpha}^{(i)}$ are focus quantities

 $V(\mathcal{B})$...the *integrability variety* of system (5)

finite number of polynomials
$$p_{\alpha}^{(s)}$$
: $\sqrt{\mathcal{B}_1} \subseteq \sqrt{\mathcal{B}_2} \subseteq \sqrt{\mathcal{B}_3} \subseteq \ldots$,
where $\mathcal{B}_k = \langle p_{\alpha}^{(1)}, \ldots, p_{\alpha}^{(n-1)} | \alpha \in \mathfrak{R}, |\alpha| \leq k, \ k \in \mathbb{N} \rangle$, stabilizes
(find *m* such that $\sqrt{\mathcal{B}_m} = \sqrt{\mathcal{B}_{m+1}}$) (Hilbert's theorem)

irreducible decomposition of V(B_m)
 ("solve": p^(s)_α = 0, α ∈ ℜ, s = 1,..., n − 1),
 different methods (Darboux method) to show V(B) = V(B_m)
 (all systems corresponding to points from V(B_m) have n − 1
 functionally independent analytic or formal first integrals)

Integrability and linearizability: (1 : -1 : -1) res. quad. sys.
Introduction
Integrability

Definition

A **Darboux factor** for the vector field \mathcal{X} is a polynomial f(x, y, z), such that

$$\mathcal{X}f = Kf,\tag{7}$$

where K(x, y, z) is also a polynomial function called **cofactor** of f. A **exponential factor** is as a function of the form

$$E(x, y, z) = e^{\frac{g(x, y, z)}{h(x, y, z)}}$$

such that g and h are coprime and $\mathcal{X}E = C_E E$ holds for some polynomial function C_E of degree at most d - 1($d = \max \operatorname{degree}(P, Q, R)$) Integrability and linearizability: (1:-1:-1) res. quad. sys. Introduction Integrability

Theorem

Suppose that \mathbb{C} -polynomial systems (1) of degree d admits p irreducible invariant algebraic curves $f_i = 0$ with cofactors K_i for i = 1, ..., p and q exponential factors $\exp(g_j/h_j)$ with cofactors L_j for j = 1, ..., q. There exist $\lambda_i, \mu_j \in \mathbb{C}$ not all zero such that $\sum_{i=1}^{p} \lambda_i K_i + \sum_{j=1}^{q} \mu_j L_j = 0$, if and only if the (multivalued) function

$$H(x, y, z) = f_1^{\lambda_1} \dots f_p^{\lambda_p} \left(\exp(g_1/h_1) \right)^{\mu_1} \dots \left(\exp(g_q/h_q) \right)^{\mu_q} \quad (8)$$

is a nontrivial first integral of systems (1) (Darboux first integral).

Integrability and linearizability: ((-1:-1) res. quad. sys.	
Introduction		
Integrability		

Definition

A function M is called an inverse **Jacobi multiplier** for the vector field \mathcal{X} if it satisfies the equation

$$\mathcal{X}(M) = Mdiv(\mathcal{X}) \Leftrightarrow div(\mathcal{X}/M) = 0.$$
 (9)

A Darboux inverse Jacobi Multiplier D must satisfy

$$\sum_{i=1}^{p} \lambda_i K_i + \sum_{j=1}^{q} \mu_j L_j = \operatorname{div} \mathcal{X} = P_x + Q_y + R_z.$$

inverse Jacobi multiplier + one first integral \Rightarrow the second first integral

Integrability and linearizability: $(1:-1:-1)$ res. quad.	sys.
Introduction	
Linearizability	

Definition

System (1) is *linearizable*: exists a transformation of variables (2) which transforms systems (1) into systems

$$\begin{aligned} \dot{x_1} &= \lambda_1 x_1 \\ \dot{y_1} &= \lambda_2 y_1 \\ \dot{z_1} &= \lambda_3 z_1. \end{aligned} \tag{10}$$

Maša Dukarić 1 , Regilene Oliveira 2 and Valery Romanovski 1,3 Integrability and linearizability: (1:-1:-1) res. quad. sys.

Introduction

Linearizability

Darboux linearizability

Definition

Darboux linearization: analytic change of variables

$$x_1 = Y_1(x, y, z), \quad y_1 = Y_2(x, y, z), \quad z_1 = Y_3(x, y, z),$$

whose inverse linearizes systems (1) and such that $Y_1(x, y, z), Y_2(x, y, z)$ and $Y_3(x, y, z)$ are of the form

$$\begin{split} Y_1(x,y,z) &= \prod_{j=0}^m f_j^{\alpha_j}(x,y,z) = x + Y_1'(x,y,z), \\ Y_2(x,y,z) &= \prod_{j=0}^m g_j^{\beta_j}(x,y,z) = y + Y_2'(x,y,z), \\ Y_3(x,y,z) &= \prod_{j=0}^m h_j^{\gamma_j}(x,y,z) = z + Y_3'(x,y,z), \end{split}$$

generalized Darboux linearization transformation such that $Y_1(x, y, z)$, $Y_2(x, y, z)$ and $Y_3(x, y, z)$ are Darboux functions Maša Dukarić¹, Regilene Oliveira² and Valery Romanovski^{1,3}

Introduction

Linearizability

Theorem

The system (1) is Darboux linearizable $\iff \exists s + 1 \ge 1$ algebraic Darboux factors $f_0, \ldots, f_s(K_0, \ldots, K_s)$, $t+1 \ge 1$ algebraic Darboux factors $g_0, \ldots, g_t(L_0, \ldots, L_t)$, and u + 1 > 1 algebraic Darboux factors $h_0, \ldots, h_u(M_0, \ldots, M_u)$: (1) $f_0(x, y, z) = x + \dots$ but $f_i(0, 0, 0) = 1$ for i > 1; (2) $g_0(x, y, z) = y + \dots$ but $g_i(0, 0, 0) = 1$ for i > 1; (3) $h_0(x, y, z) = z + \dots$ but $h_i(0, 0, 0) = 1$ for i > 1; and (4) there are s + t + u constants α_i , β_j , γ_k , i = 1, ..., s, j = 1, ..., t and k = 1, ..., u $K_0 + \alpha_1 K_1 + \ldots + \alpha_s K_s = \lambda_1$ $L_0 + \beta_1 L_1 + \ldots + \beta_t L_t = \lambda_2$ $M_0 + \gamma_1 M_1 + \ldots + \gamma_n M_n = \lambda_3$

The Darboux linearization of systems (1) is given by

$$x_1 = f_0 f_1^{\alpha_1} \dots f_s^{\alpha_s}, \ y_1 = g_0 g_1^{\beta_1} \dots g_t^{\beta_t}$$
 and $z_1 = h_0 h_1^{\gamma_1} \dots h_u^{\gamma_u}.$

INTEGRABILITY and LINEARIZABILITY of the system

$$\dot{x} = x + a_{12}xy + a_{13}xz + a_{23}yz = P_1(x, y, z) \dot{y} = -y + b_{12}xy + b_{13}xz + b_{23}yz = Q_1(x, y, z) \dot{z} = -z + c_{12}xy + c_{13}xz + c_{23}yz = R_1(x, y, z).$$
(11)

Maša Dukarić 1 , Regilene Oliveira 2 and Valery Romanovski 1,3 Integrability and linearizability: (1:-1:-1) res. quad. sys.

```
Integrability and linearizability: (1:-1:-1) res. quad. sys.
Results
```

Theorem: Integrability

Theorem (Integrability)

The quadratic three dimensional system (11) is locally integrable if and only if one of the following conditions is satisfied (1) $c_{13} = c_{12} = b_{13} = b_{12} = 0$: (2) $c_{23} = c_{12} = b_{23} = b_{13} = b_{12} + c_{13} = a_{13} = a_{12} = 0;$ (3) $c_{12} = b_{13} = a_{23} = a_{12}b_{23} + a_{13}c_{23} + b_{23}c_{23} = 0$ $a_{13}b_{12} - a_{13}c_{13} - b_{23}c_{13} = a_{12}b_{12} - a_{12}c_{13} + b_{12}c_{23} = 0;$ (4) $c_{23} = c_{13} = c_{12} = b_{12} = a_{13} - b_{23} = a_{12} = 0;$ (5) $c_{23} = b_{23} = a_{23} = a_{13} = a_{12} = 0$; (6) $c_{13} = b_{23} = b_{13} = b_{12} = a_{13} = a_{12} - c_{23} = 0.$

Results

Theorem: Integrability

$$\Phi(x, y, z) = xy(1 + O(x, y, z)) \text{ and } \psi(x, y, z) = xz(1 + O(x, y, z))$$

• computed the first 11 focus quantities of $\mathcal{X}\Phi(x, y, z)$, f_i , and

$$\mathcal{X}\psi(x,y,z), g_j$$
:

$$\begin{split} f_1 &= (a_{13} + b_{23})c_{12}; \\ f_2 &= -2a_{13}b_{12} - b_{12}b_{23} + b_{12}(a_{13} + b_{23}) + (a_{13} + b_{23})c_{13} + \\ -b_{13}c_{23}; \\ f_3 &= -2a_{13}b_{13} + b_{13}(a_{13} + b_{23}); \dots \\ g_1 &= -2a_{12}c_{12} + c_{12}(a_{12} + c_{23}); \\ g_2 &= -(b_{23}c_{12}) - 2a_{12}c_{13} - c_{13}c_{23} + b_{12}(a_{12} + c_{23}) + \\ +c_{13}(a_{12} + c_{23}); \\ g_3 &= b_{13}(a_{12} + c_{23}); \dots \end{split}$$

- not unique focus quantities (free coefficients equal to zero)
- irreducible decomposition (Singular routine minAssGTZ); $B_{11} = \langle f_1, f_2, f_3, \dots, f_{11}, g_1, g_2, g_3, \dots, g_{11} \rangle$

Results

Theorem: Integrability

Darboux integrability

Case 2

$$\dot{x} = x + a_{23}yz \ \dot{y} = -y(1-b_{12}x) \ \dot{z} = -z(1+b_{12}x)$$

Darboux factors: $l_1 = y$, $l_2 = z$, $l_3 = x + \frac{a_{23}}{3}yz$ Exponential factor: $l_4 = e^{2x+a_{23}yz}$ First integrals:

$$\phi(x, y, z) = l_2 l_3 l_4^{\frac{b_{12}}{2}} = xz(1 + O(x, y, z))$$

$$\psi(x, y, z) = l_1 l_2 l_3^2$$

 ψ (not in the wanted form) \rightarrow $(\psi/\phi)(x,y,z) = xy(1+O(x,y,z))$

Maša Dukarić¹, Regilene Oliveira² and Valery Romanovski^{1,3}

Integrability and linearizability:	(1:-1:-1) res. quad. sys.	
Results		

Theorem: Integrability

Case 3

$$\dot{x} = x(1 + a_{12}y + a_{13}z) \dot{y} = y(-1 + b_{12}x + b_{23}z) \dot{z} = z(-1 + \frac{a_{13}b_{12}}{a_{13} + b_{23}}x - \frac{a_{12}b_{23}}{a_{13} + b_{23}}y)$$

change of variables $x \mapsto y, y \mapsto x, z \mapsto z$ and time rescaling \Rightarrow systems studied by W. Aziz, C. Christopher [2] [Theorem 4]

Prove of sufficiency of conditions:

$$\mathsf{Linearizability} \Longrightarrow \mathsf{Integrability}$$

Results

Theorem: Linearizability

Theorem (Linearizability)

The system (11) is linearizable if and only if either one of the conditions (1),(2),(4),(5),(6) from Theorem on Integrability is satisfied or one of two following conditions holds (7) $c_{12} = b_{13} = b_{12} = b_{23} = a_{23} = a_{13} = a_{12} = 0$

$$(8) \ b_{13} = c_{13} = c_{12} = c_{23} = a_{23} = a_{13} = a_{12} = 0$$

```
Integrability and linearizability: (1:-1:-1) res. quad. sys.
```

Results

Theorem: Linearizability

Necessary conditions

computing linearizability quantities; computing the irreducible decomposition (Singular routine minAssGTZ)

Results

Theorem: Linearizability

Case 1: $c_{13} = c_{12} = b_{13} = b_{12} = 0$

$$\dot{x} = x + a_{12}xy + a_{13}xz + a_{23}yz
\dot{y} = y(-1 + b_{23}z)$$

$$\dot{z} = z(-1 + c_{23}y)$$
(12)

 $\dot{y}, \dot{z}...$ linearizable node \Rightarrow transformation $\Rightarrow \dot{Y} = -Y, \dot{Z} = -Z$ looking for $X = \alpha(Y, Z) + \beta(Y, Z)x$ such that $\dot{X} = X \Rightarrow$

$$\dot{\alpha} + \beta a_{23}yz = \alpha, \quad \dot{\beta} + \beta (a_{12}y + a_{13}z) = 0$$
 (13)

 $\underline{\mathsf{Maša}\ \mathsf{Dukarić}^1}, \ \mathsf{Regilene\ Oliveira}^2 \ \text{ and } \ \mathsf{Valery\ Romanovski}^{1,3} \qquad \mathsf{Integrability\ and\ linearizability:}\ (1:-1:-1) \ \mathsf{res.\ quad.\ sys.}$

Results

Theorem: Linearizability

Case 2:
$$c_{23} = c_{12} = b_{23} = b_{13} = b_{12} + c_{13} = a_{13} = a_{12} = 0$$

$$X = x + \frac{a_{23}}{3}yz$$
$$Y = ye^{-b_{12}x - \frac{a_{23}b_{12}}{2}yz}$$
$$Z = ze^{b_{12}x + \frac{a_{23}b_{12}}{2}yz}$$

Transformation of cases

Case 4 \Leftrightarrow Case 6 Case 7 \Leftrightarrow Case 8

Remark

some invariant curves obtained from first integrals (proof of integrability)

<u>Maša Dukarić</u>¹, Regilene Oliveira² and Valery Romanovski^{1,3} Integrability and

Results

Theorem: Existence of the first integral xy(1 + O(x, y, z))

Theorem (First integral xy(1 + O(x, y, z)))

Necessary conditions for three dimensional system (11) with $a_{23} = 0$ to have a first integral in the form xy(1 + O(x, y, z)) are (1) $c_{12} = b_{13} = a_{13}b_{12} - a_{13}c_{13} - b_{23}c_{13} = 0$; (2) $c_{13} = c_{12} = a_{13} - b_{23} = b_{12}b_{23} + b_{13}c_{23} = 0$ (7) $c_{23} = b_{23} = a_{13} = 0$; (8) $b_{23} = b_{13} = a_{13} = 0$; (9) $c_{13} = b_{13} = b_{12} = a_{13} + b_{23} = 0$; (10) $b_{13} = b_{12} = a_{13} + b_{23} = a_{12} = 0$; (11) $b_{13} = b_{12} = a_{13} + b_{23} = b_{23}c_{12} + a_{12}c_{13} = 0;$ (12) $b_{13} = b_{12} = a_{13} + b_{23} = b_{23}c_{12} + c_{13}c_{23} = 0;$

```
Integrability and linearizability: (1 : -1 : -1) res. quad. sys.

Results

Theorem: Existence of the first integral xy(1 + O(x, y, z))
```

Computation of the necessary conditions for existence one first integral in the form xy(1 + O(x, y, z))similar way as for Theorem (8) computed first few focus quantities, appearing free coefficientsresonant coefficients (denoted as p1, p2, p3, ...)first three focus quantities (f_1, f_2, f_3) were presented before and in f_4 appear free conditions

$$f_4 = (b_{12}(9a_{12}^2b_{12} + 6a_{12}a_{13}c_{12} - a_{23}b_{12}c_{12} + 9a_{12}b_{23}c_{12} + a_{23}c_{12}c_{13} + 3a_{13}c_{12}c_{23} + 3b_{23}c_{12}c_{23} + 12a_{12}p_1))/2 + \dots$$

```
Integrability and linearizability: (1 : -1 : -1) res. quad. sys.
Results
Theorem: Existence of the first integral xy(1 + O(x, y, z))
```

eliminating free coefficients from first thirteen focus quantities (Singular routine Eliminate- laborious routine) Elimination Theorem

Eliminate: geometrically: projection P of the variety of ideal $F = \langle f_1, \ldots, f_{13} \rangle$ on the space of parameters computing irreducible decomposition (minAssGTZ)

 \Rightarrow twelve cases

Computational problems: difficult to compute over the field of rational numbers $\Rightarrow a_{23} = 0$; modular arithmetics [4] \Rightarrow one condition incorrect (5') $c_{12} = 152b_{12} + 13c_{13} = a_{13} - b_{23} = 39a_{12} + 7c_{23} = 71b_{23}c_{13} - 135b_{13}c_{23} = 0$ (corrected: adding $c_{13}b_{23} = 0$)

```
Integrability and linearizability: (1 : -1 : -1) res. quad. sys.

Results

Theorem: Existence of the first integral xy(1 + O(x, y, z))
```

Remark 1

 $\bullet\,$ used modular arithmetics $\Rightarrow\,$ can not guarantee that the list of conditions is complete

Remark 2

• proof of sufficiency done only for three cases: Darboux integrability

```
Integrability and linearizability: (1 : -1 : -1) res. quad. sys.

Results

Theorem: Existence of the first integral xy(1 + O(x, y, z))
```

Remark 3

- complete integrability: resonant coefficients all zero
- one first integral: resonant coefficient can not be equal to zero Explanation:
 - resonant coefficients equal to zero; minimal decomposition: 7 conditions (J_1, \ldots, J_7)
 - resonant coefficient free; first elimination of res. coef., then minimal decomposition: 12 conditions (I_1, \ldots, I_{12})
 - $M_1 = \bigcap_{i=1}^7 J_i, M_2 = \bigcap_{i=1}^{12} I_i;$ comparison: Reduce $(M_1, M_2) = 0 \iff M_1 \subset M_2$

Conclusion

Conclusion

$$\dot{x} = x + a_{12}xy + a_{13}xz + a_{23}yz \dot{y} = -y + b_{12}xy + b_{13}xz + b_{23}yz \dot{z} = -z + c_{12}xy + c_{13}xz + c_{23}yz$$

- Two independent first integrals of (11): 6 cases
- Linearizable systems (11): 7 cases
- One first integral of (11): 12 cases \Rightarrow interesting observation

Conclusion

M. DUKARIĆ, R. OLIVEIRA, V. ROMANOVSKI, Local integrability and linearizability of a (1 : -1 : -1) resonant quadratic system, submitted.



W. AZIZ, C. CHRISTOPHER, *Local integrability and linearizability of three-dimensional Lotka-Volterra systems*, Applied Mathematics and Computations **219** (2012), no. 8, 4067–4081.



W. AZIZ, *Integrability and Linearizability of Three dimensional vector fields*, To appear in Qual. Theory of Dyn. Syst.(2014).

V.G. ROMANOVSKI, M. PREŠERN, An approach to solving systems of polynomials via modular arithmetics with applications, J. Comput. Appl. Math. **236** (2011), no. 2, 196–208.



L. R. BERRONE, H. GIACOMINI, *Inverse Jacobi multipliers*, Rend. Circ. Math. Palermo 3 (2003), 77-103.

Conclusion

Thank you for your attention!

 $\frac{Maša \ Dukaric^{1}}{2}, Regilene \ Oliveira^{2} \ and \ Valery \ Romanovski^{1,3} = Integrability \ and \ Iinearizability: (1:-1:-1) \ res. \ quad. \ sys.$